

Simulation of Stochastic Visual Motion Observer



July 23

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Purpose of this simulations

Stability analysis of Stochastic VMO

Modifications

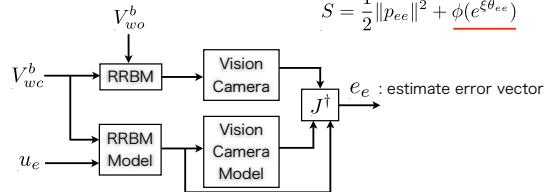
1. V_{wo}^b : brownian motion

2. error feedback gain

$$u_e = -k_e \begin{bmatrix} 1 & 0 \\ 0 & \frac{4}{4-\phi(e^{\hat{\xi}\theta_{ee}})} \end{bmatrix} e_e$$

Storage Function of the estimate error system

$$S = \frac{1}{2} \|p_{ee}\|^2 + \underline{\phi(e^{\hat{\xi}\theta_{ee}})}$$



|人| Purpose (2)

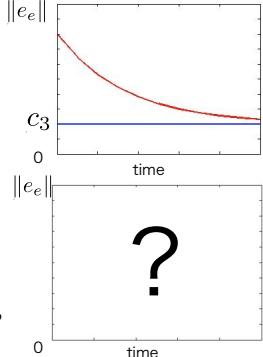
How to decrease $\|e_e\|$ in the simulation

Theoretically:

$$c_3 = \frac{\text{tr}(\Sigma \Sigma^T)}{4k_e}$$

 Σ : covariance matrix

$$\Sigma = \begin{bmatrix} 0.1 & 0 & 0 & 0.01 & 0 & 0 \\ 0 & 0.1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0.01 & 0 & 0 & 0 \\ 0.01 & 0 & 0 & 0.01 & 0.01 & 0 \\ 0 & 0 & 0 & 0.01 & 0.01 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0.01 \end{bmatrix}$$



|人| Wiener process

Definition

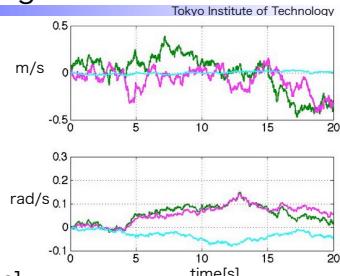
i)stationary independent increments

ii) the increments follows the normal distribution

expected value $E[w(t) - w(s)] = 0$ variance $E[\{w(t) - w(s)\}^2] = \sigma^2 |t - s|$

|人| Simulation settings

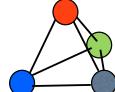
$$V_{wo}^b = \begin{bmatrix} V_x \\ V_y \\ V_z \\ W_x \\ W_y \\ W_z \end{bmatrix}$$



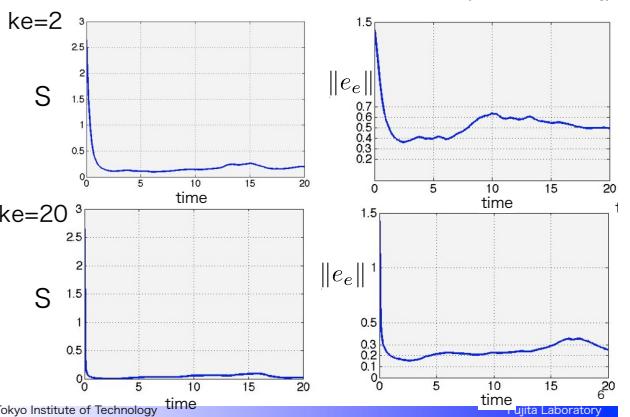
simulation time : 20[sec]

sampling time : 0.01[sec]

the number of each trials : 20



|人| Example result

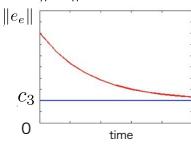


|人| Simulation results

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Comparison about the means of S and $\|e_e\|$ in each ke

$$u_e = -k_e \begin{bmatrix} 1 & 0 \\ 0 & \frac{4}{4-\phi(e^{\xi \theta_{ee}})} \end{bmatrix} e_e$$



ke \	0.2	2.0	20	50
S	67.1	1.51	0.17	0.62
$\ e_e\ $	2.69	0.65	0.27	0.38
C ₃	2.6×10^{-2}	2.6×10^{-3}	0	0

S and $\|e_e\|$ are the smallest

when ke is 20

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|人| Conclusion

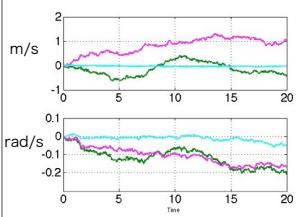
- Storage Function can be kept small as ke becomes small

- The limit of ke depends on sampling time

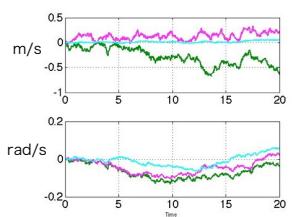
Covariance matrix? $\Sigma = \begin{bmatrix} 0.1 & 0 & 0 & 0.01 & 0 & 0 \\ 0 & 0.1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0.01 & 0 & 0 & 0 \\ 0.01 & 0 & 0 & 0.01 & 0.01 & 0 \\ 0 & 0 & 0 & 0.01 & 0.01 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0.01 \end{bmatrix}$

|人| Failure example

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Successive large input



Large input?

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What cause VMO to fail?