

Equilibrium assignment of Transportation Network



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Introduction

Highway congestion

Highway congestion is imposing an intolerable burden on many urban residents

Congestion occurs when the demand for travel exceeds highway capacity



Action

There are some approaches to reducing congestion such as vehicle control, raising tolls or taxes etc..

All approaches boil down to the controlling highway capacity



P. Varaiya, "Smart Cars on Smart Roads: Problems of Control",
IEEE Transactions on Automatic Control, Vol. 38, No. 2, Feb. 1993



Beginning

G. Como, K. Savla, D. Acemoglu, M. A. Dahleh and E. Frazzoli:
"On Robustness Analysis of Large-scale Transportation Networks,"
International Symposium on Mathematical Theory of Networks and Systems,
Budapest, Hungary, 2399-2406, 2010

Introduction

- Robustness analysis of transportation network
- Deriving upper and lower bound of stability margin
- Robustness price of anarchy



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Outline

- Introduction
- Problem Formulation
Transportation network
Route choice behavior
- Equilibrium Assignment Problem
User equilibrium with fixed demand
System optimum
- Conclusion



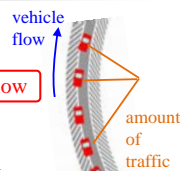
Congestion Avoid

Highway capacity

To improve Highway capacity,

assign amount of traffic

increase vehicle flow

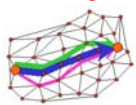


Traffic assignment problem

Transportation network

Highway is considered as a kind of network

→ User equilibrium assignment
System optimum assignment



Vehicle control

Longitudinal control

Each vehicle should keep a fixed distance of the precede
→ String stability



Lateral control

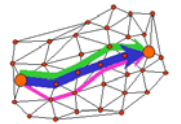
Vehicles seek to change a less crowded lane



Traffic Assignment Problem

Transportation network

Transportation network is a network of roads, streets and considered as a type of directed graph



Traffic assignment problem

- Concerning the traffic flow between origins and destinations in transportation networks
- To enable vehicles to reach destination in the shortest possible time using the maximum roadway capacity

Wardrop equilibrium

User equilibrium assignment System optimum assignment



Problem Formulation

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Notations

Directed graph

Transportation network is described by a **Directed graph** $G[N, A]$

N : Set of **nodes**

→ Expressing City, Crossing etc..

A : Set of **links**

→ Expressing Road

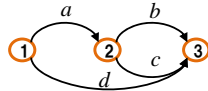
Origin-Destination(OD)

$R \in N$: Set of **origin nodes**

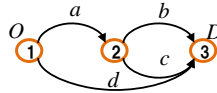
$S \in N$: Set of **destination nodes**

$K_{rs}, r \in R, s \in S$

: Set of **simple route**



$N : 1, 2, 3$
 $A : a, b, c, d$



$R : 1$
 $S : 3$
 $K_{13} : [a, b], [a, c], [d]$

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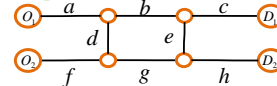
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Problem Formulation

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Example



$R : O_1, O_2$

$S : D_1, D_2$

$A : a, b, c, d, e, f, g, h$

$K_{O_1D_1} : k_1 = [a, b, c], k_2 = [a, d, g, e, c]$ $K_{O_1D_2} : k_1 = [a, d, g, h], k_2 = [a, b, e, h]$

$K_{O_2D_1} : k_1 = [f, d, b, c], k_2 = [f, g, e, c]$ $K_{O_2D_2} : k_1 = [f, g, h], k_2 = [f, d, b, e, h]$

Traffic flow

Flow [pcu/min]

f_k^{rs} : **Traffic flow** of route k

x_a : **Traffic flow** of link a

pcu: passenger car unit

Cost [min]

t_a : **Cost** on link a

c_k^{rs} : **Time** taken to traverse route k

Example

$$x_b = f_1^{O_1D_1} + f_2^{O_1D_2} + f_1^{O_2D_1} + f_2^{O_2D_2} \quad c_2^{12} = t_a + t_d + t_g + t_e + t_c$$

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Problem Formulation

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Notations

Flow

$x_a, a \in A$: **Traffic flow** of link a

$f_k^{rs}, r \in R, s \in S, k \in K_{rs}$
: **Traffic flow** of route k

Cost

$t_a = t_a(x_a)$: **Cost** on link a

→ Expressing Toll, Time etc..

c_k^{rs} : **Time** taken to traverse route k

Relational expression

$$x_a = \sum_{rs} \sum_k \delta_{a,k}^{rs} f_k^{rs} \quad c_k^{rs} = \sum_{a \in A} \delta_{a,k}^{rs} t_a(x_a)$$

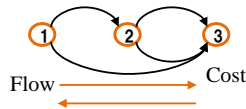
$$\sum_k f_k^{rs} = Q_{rs}$$

$$f_k^{rs} \geq 0$$

$$t_a(x_a) \geq 0$$

Q_{rs} : **OD traffic flow**

$\delta_{a,k}^{rs}$: **Identification variable**



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Route Choice Behavior

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User model

Rational model

- Each user non-cooperatively seeks to **minimize his cost** of transportation
- Each user has a **full information** about all available routes
- **All or nothing network loading**

Stochastic rational model

- It's not always true that
 - each user non-cooperatively seeks to **minimize his cost** of transportation
 - each user has a **full information** about all available routes
- There is an **error** in observation data
- **Stochastic network loading**
 - Logit model
 - Probit model



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Outline

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- Introduction
- Problem Formulation
 - Transportation network
 - Route choice behavior
- **Equilibrium Assignment Problem**
 - User equilibrium with fixed demand
 - System optimum
- Conclusion

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User Equilibrium

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Wardrop equilibrium

Wardrop's first principle

The journey times in all routes actually used are equal and less than those which would be experienced by a single vehicle on any unused route

Wardrop's second principle

At equilibrium the average journey time is minimum

Assumption

- Each user non-cooperatively seeks to minimize his cost of transportation
- Each user has a full information about all available routes

User equilibrium

No user can minimize his journey time by unilaterally changing his or her route

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User Equilibrium with Fixed Demand

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User equilibrium with fixed demand

Assumption

- Fixed demand
- Each user chooses his route by Wardrop's first principle

Formulation of User equilibrium

$$\text{If } f_k^{rs} > 0, c_k^{rs} = c_{rs} \quad \forall k \in K_{rs}, \forall r \in R, \forall s \in S$$

$$\text{If } f_k^{rs} = 0, c_k^{rs} \geq c_{rs} \quad \forall k \in K_{rs}, \forall r \in R, \forall s \in S$$

$$c_k^{rs} = \sum_{a \in A} \delta_{a,k}^{rs} t_a(x_a)$$

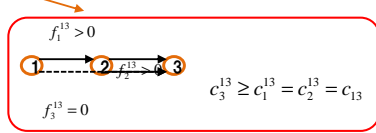
$$x_a = \sum_k \sum_{rs} \delta_{a,k}^{rs} f_k^{rs}$$

Constraint

$$\sum_k f_k^{rs} = Q_{rs}$$

$$f_k^{rs} \geq 0$$

c_{rs} : Shortest time taken to traverse set of route rs



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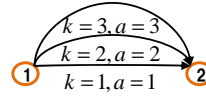


User Equilibrium with Fixed Demand

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Example

Problem



Cost function

$$t_1 = 5 + 0.1f_1$$

$$t_2 = 10 + 0.025f_2$$

$$t_3 = 15 + 0.025f_3$$

$$Q_{12} = 200$$

$$f \text{ [pcu/min]}$$

pcu: passenger car unit

$$t \text{ [min]}$$

Optimal problem

Want to get f_k^{rs} to satisfy User equilibrium

Find minimum c_k^{rs}

$$\text{Constraint } c_k^{rs} = \sum_{a \in A} \delta_{a,k}^{rs} t_a(x_a) \quad x_a = \sum_k \sum_{rs} \delta_{a,k}^{rs} f_k^{rs}$$

$$\sum_k f_k^{rs} = Q_{rs}$$

$$f_k^{rs} \geq 0$$

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User Equilibrium with Fixed Demand

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Mathematical optimization problem

Nonlinear optimal problem with constraints

$$\min Z_p = \sum_{a \in A} \int_0^{x_a} t_a(w) dw$$

Constraint

$$\sum_k f_k^{rs} - Q_{rs} = 0 \quad x_a = \sum_k \sum_{rs} \delta_{a,k}^{rs} f_k^{rs}$$

$$f_k^{rs} \geq 0$$

$$x_a \geq 0$$

Karush-Kuhn-Tucker condition

$$\text{If } f_k^{rs} > 0, \frac{\partial L(f^*, \lambda^*)}{\partial f_k^{rs}} = 0 \quad \text{If } f_k^{rs} = 0, \frac{\partial L(f^*, \lambda^*)}{\partial f_k^{rs}} \geq 0 \quad \frac{\partial L(f^*, \lambda^*)}{\partial \lambda_{rs}} = 0$$

Lagrangian function

$$L(f, \lambda) = Z_p(f) - \sum_{rs} \lambda_{rs} \{ \sum_k f_k^{rs} - Q_{rs} \} \quad f_k^{rs} \geq 0$$

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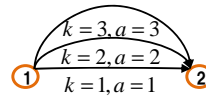


User Equilibrium with Fixed Demand

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Example

Problem



Cost function

$$t_1 = 5 + 0.1f_1$$

$$t_2 = 10 + 0.025f_2$$

$$t_3 = 15 + 0.025f_3$$

$$Q_{12} = 200$$

$$f \text{ [pcu/min]}$$

pcu: passenger car unit

$$t \text{ [min]}$$

Optimal problem

$$\min Z_p = 5f_1 + 0.05f_1^2 + 10f_2 + 0.0125f_2^2 + 15f_3 + 0.0125f_3^2$$

$$\text{s.t. } \sum_{k=1}^3 f_k = 200 \quad f_k \geq 0 (k=1 \sim 3)$$

Karush-Kuhn-Tucker condition

$$L(f, \lambda) = 5f_1 + 0.05f_1^2 + 10f_2 + 0.0125f_2^2 + 15f_3 + 0.0125f_3^2$$

$$- \lambda (\sum_{k=1}^3 f_k - 200)$$

$$f_k \geq 0 (k=1 \sim 3)$$

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User Equilibrium with Fixed Demand

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$$t_1 : 5 + 0.1f_1 = \lambda (f_1 \geq 0) \text{ or } 5 + 0.1f_1 \geq \lambda (f_1 = 0)$$

$$t_2 : 10 + 0.025f_2 = \lambda (f_2 \geq 0) \text{ or } 10 + 0.025f_2 \geq \lambda (f_2 = 0)$$

$$t_3 : 15 + 0.025f_3 = \lambda (f_3 \geq 0) \text{ or } 15 + 0.025f_3 \geq \lambda (f_3 = 0)$$

$$\sum_{k=1}^3 f_k - 200 = 0$$

Search optimal solution

Case1: User chooses only Route 1

$$f_1 = 200, f_2 = 0, f_3 = 0, t_1 = 25, t_2 = 10, t_3 = 15$$

$$\rightarrow Z_p = 3000, \lambda = t_1$$

$$\lambda > t_2, t_3 \text{ Not optimal!}$$

Case2: User chooses Route 1,2

$$t_1 = t_2 = \lambda, f_3 = 0, \sum_{k=1}^3 f_k - 200 = 0$$

$$\rightarrow f_1 = 80, f_2 = 120, f_3 = 0, t_1 = 13, t_2 = 13, t_3 = 15,$$

$$Z_p = 2100, \lambda = t_1, t_2$$

$$\lambda < t_3 \text{ Optimal!}$$

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System Optimum

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Wardrop equilibrium

Wardrop's first principle

The journey times in all routes actually used are equal and less than those which would be experienced by a single vehicle on any unused route.

Wardrop's second principle

At equilibrium the average journey time is minimum

Assumption

- Routes of all vehicles are controlled by the system
- Routing is based on maximum utilization of resources and minimum travel time

System optimum

All routes between a given OD pair have the same marginal travel time

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System Optimum

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Mathematical optimization problem

Nonlinear optimal problem with constraints

$$\min Z_s = \sum_{a \in A} x_a t_a(x_a)$$

Constraint

$$\sum_k f_k^{rs} - Q_{rs} = 0 \quad x_a = \sum_k \sum_{rs} \delta_{a,k}^{rs} f_k^{rs}$$
$$f_k^{rs} \geq 0 \quad x_a \geq 0$$

$$\min Z_s = \sum_{a \in A} x_a t_a(x_a) = \sum_{a \in A} \int_0^{x_a} [t_a(w) + w \frac{d\{t_a(w)\}}{dw}] dw \quad \text{Product rule}$$
$$= \sum_{a \in A} \int_0^{x_a} [t_a(w) + w \frac{d\{t_a(w)\}}{dw}] dw$$

→ This optimal problem can solve the same way as **User equilibrium with fixed demand**

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User Equilibrium ⇔ System Optimum

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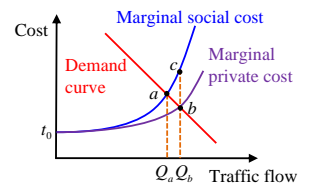
Aspect

User equilibrium

→ Marginal private cost

System optimum

→ Marginal social cost



At the equilibrium point,

Each user's cost is **b** under **user equilibrium**, and social cost is **c**

Social cost is **a** under **social optimum**

→ **Social optimum is better than user equilibrium from the social cost**

$$\text{User equilibrium} \quad \min Z_p = \sum_{a \in A} \int_0^{x_a} t_a(w) dw$$

$$\text{System optimum} \quad \min Z_s = \sum_{a \in A} \int_0^{x_a} [t_a(w) + w \frac{d\{t_a(w)\}}{dw}] dw$$

A kind of **congestion toll**

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Conclusion

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Summary

• Problem formulation

Transportation network
Route choice behavior

• Equilibrium assignment problem

- User equilibrium with fixed demand
- System optimum

Future works

• Equilibrium assignment problem

- Stochastic user equilibrium
- User equilibrium with variable demand

• Solution method of user equilibrium

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Appendix

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Karush-Kuhn-Tucker Conditions

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Example $\min f(x) = (x_1 - 1)^2 + (x_2 - 2)^2$

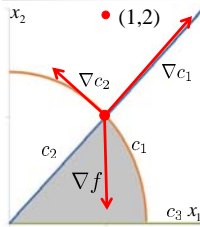
constraints $c_1(x) = x_1^2 + x_2^2 - 2 \leq 0$ **strictly convex**

$$c_2(x) = -x_1 + x_2 \leq 0$$

$$c_3(x) = -x_2 \leq 0$$

$$\nabla f(x^*) - u_1^* \nabla c_1(x^*) - u_2^* \nabla c_2(x^*) = 0$$

$$\begin{pmatrix} 2(x_1^* - 1) \\ 2(x_2^* - 2) \end{pmatrix} + u_1^* \begin{pmatrix} 2x_1^* \\ 2x_2^* \end{pmatrix} + u_2^* \begin{pmatrix} -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -2 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 2 \\ 2 \end{pmatrix} + \begin{pmatrix} -1 \\ 1 \end{pmatrix} = 0$$



Karush-Kuhn-Tucker Conditions

$$L(x, \lambda) = \sum_{r \in S} U_r(x_r) - \sum_{r: l \in r} \lambda_r (x_r - c_r) \quad \lambda_r \geq 0$$

the optimal value x^* and constraint's grad is Linear independence, then there exists constants λ_r such that

$$\frac{\partial L(x^*)}{\partial x} = 0 \quad \lambda_r (x_r - c_r) = 0$$

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Karush-Kuhn-Tucker Conditions (General Form)

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$$\max_x f(x) \quad \text{s.t. } g_i(x) \leq 0$$
$$h_j(x) = 0$$

the Lagrangian

$$L(x, \lambda, \mu) = f(x) - \sum_i \lambda_i g_i(x) + \sum_j \mu_j h_j(x)$$

Suppose there exists constants $\lambda_i \geq 0$ and μ_j such that

$$\frac{\partial f}{\partial x_k}(x^*) - \sum_i \lambda_i \frac{\partial g_i}{\partial x_k}(x^*) + \sum_j \mu_j \frac{\partial h_j}{\partial x_k}(x^*) = 0, \quad \forall k$$

$$\lambda_i g_i(x^*) = 0, \quad \forall i$$

→ the first-order necessary condition for optimality

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Uniqueness of User Equilibrium with Fixed Demand

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Nonlinear optimal problem with constraints

$$\min Z_p = \sum_{a \in A} \int_0^{x_a} t_a(w) dw$$

Constraint

$$\sum_k f_k^{rs} - Q_{rs} = 0 \quad x_a = \sum_k \sum_{rs} \delta_{a,k}^{rs} f_k^{rs} \quad f_k^{rs} \geq 0 \quad x_a \geq 0$$

$$\frac{\partial Z_p}{\partial x_a} = t_a(x_a)$$

$$\frac{\partial^2 Z_p}{\partial x_a \partial x_b} = \begin{cases} \frac{dt_a(x_a)}{dx_a} > 0 (a=b) \\ 0 (a \neq b) \end{cases} \quad \therefore \nabla^2 Z_p = \begin{bmatrix} \frac{dt_1(x_1)}{dx_1} & \dots & 0 \\ \vdots & \frac{dt_a(x_a)}{dx_a} & \vdots \\ 0 & \dots & \frac{dt_n(x_n)}{dx_n} \end{bmatrix}$$

Cost function is monotonic increase $\frac{dt_a(x_a)}{dx_a} > 0$

$$\mathbf{h} \neq \mathbf{0} \text{ s.t. } \mathbf{h}(\nabla^2 Z_p)\mathbf{h} = \sum_{a \in A} h_a^2 \frac{dt_a(x_a)}{dx_a} > 0 \quad Z_p \text{ is convex function}$$

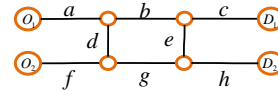
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Problem Formulation

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Example



$R: O_1, O_2$

$S: D_1, D_2$

$A: a, b, c, d, e, f, g, h$

$$K_{O_1 D_1}: k_1 = [a, b, c], k_2 = [a, d, g, e, c] \quad K_{O_1 D_2}: k_1 = [a, d, g, h], k_2 = [a, b, e, h]$$

$$K_{O_2 D_1}: k_1 = [f, d, b, c], k_2 = [f, g, e, c] \quad K_{O_2 D_2}: k_1 = [f, g, h], k_2 = [f, d, b, e, h]$$

$$x_a = \sum_{rs} \sum_k \delta_{a,k}^{rs} f_k^{rs} \quad x_a: \text{Traffic flow of link } a$$

$$= f_1^{O_1 D_1} + f_2^{O_1 D_1} + f_1^{O_1 D_2} + f_2^{O_1 D_2} \quad f_k^{rs}: \text{Traffic flow of route } k$$

$$c_2^{12} = \sum_{a \in A} \delta_{a,2}^{12} t_a(x_a) \quad t_a(x_a): \text{Cost on link } a$$

$$= t_a(x_a) + t_d(x_d) + t_g(x_g) + t_e(x_e) + t_c(x_c) \quad c_k^{rs}: \text{Time of route } k$$

$$\delta_{a,k}^{rs}: \text{Identification variable}$$

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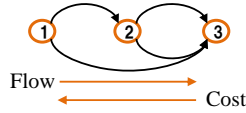
Problem Formulation

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Flow

$x_a, a \in A$: Traffic flow of link a

$f_k^{rs}, r \in R, s \in S, k \in K_{rs}$
: Traffic flow of route k



Cost

$t_a = t_a(x_a)$: Cost on link a

→ Expressing Toll, Time etc..

c_k^{rs} : Time taken to traverse route k

Relational expression

$$x_a = \sum_{rs} \sum_k \delta_{a,k}^{rs} f_k^{rs} \quad c_k^{rs} = \sum_{a \in A} \delta_{a,k}^{rs} t_a(x_a)$$

$$\sum_k f_k^{rs} = Q_{rs} \quad t_a(x_a) \geq 0 \quad Q_{rs}: \text{OD traffic flow}$$

$$f_k^{rs} \geq 0 \quad \delta_{a,k}^{rs}: \text{Identification variable}$$

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User Equilibrium with Fixed Demand

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Mathematical optimization problem

Nonlinear optimal problem with constraints

$$\min Z_p = \sum_{a \in A} \int_0^{x_a} t_a(w) dw$$

Constraint

$$\sum_k f_k^{rs} - Q_{rs} = 0 \quad x_a = \sum_k \sum_{rs} \delta_{a,k}^{rs} f_k^{rs}$$

$$f_k^{rs} \geq 0 \quad x_a \geq 0$$

↓ Karush-Kuhn-Tucker condition

$$\text{If } f_k^{rs} > 0, \frac{\partial L(f^*, \lambda^*)}{\partial f_k^{rs}} = 0 \quad \text{If } f_k^{rs} = 0, \frac{\partial L(f^*, \lambda^*)}{\partial f_k^{rs}} \geq 0 \quad \frac{\partial L(f^*, \lambda^*)}{\partial \lambda_{rs}} = 0$$

Lagrangian function

$$L(f, \lambda) = Z_p(f) - \sum_{rs} \lambda_{rs} \{ \sum_k f_k^{rs} - Q_{rs} \} \quad f_k^{rs} \geq 0$$

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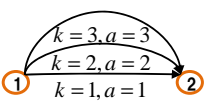
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User Equilibrium with Fixed Demand

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Example

Problem



Cost function

$$t_1 = 5 + 0.1f_1$$

$$t_2 = 10 + 0.025f_2$$

$$t_3 = 15 + 0.025f_3$$

$$Q_{12} = 200$$

f [pcu/min]

pcu: passenger car unit

t [min]

Optimal problem

$$L(f, \lambda) = 5f_1 + 0.05f_1^2 + 10f_2 + 0.0125f_2^2 + 15f_3 + 0.0125f_3^2$$

$$\text{s.t. } \sum_{k=1}^3 f_k = 200 \quad f_k \geq 0 (k=1 \sim 3)$$

↓ Karush-Kuhn-Tucker condition

$$L(f, \lambda) = 5f_1 + 0.05f_1^2 + 10f_2 + 0.0125f_2^2 + 15f_3 + 0.0125f_3^2$$

$$- \lambda (\sum_{k=1}^3 f_k - 200) \quad f_k \geq 0 (k=1 \sim 3)$$

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