

Primal-Dual Algorithm for Utility Maximization



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 FL 10 - 06 - 01
 7th, June, 2010



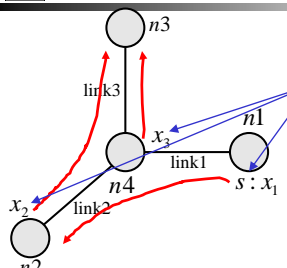
Outline

Network Optimization and Control
 Srinivas Shakkottai and R. Srikant
 Foundations and Trends in Networking,
 Vol.2, No.3, 2007.

- Background
- Primal Algorithm
- Dual Algorithm
- Primal-Dual Algorithm
- Power network



Background - Network



Network

S : traffic source
 each source is associated with a route r
 x_r : rate of source route r 's transmission
 $U_r(x_r)$: the utility that the source obtains from transmitting data on route r at rate x_r

example

Utility $U_r(x_r) = \omega_r \log x_r$
 Constraints $x_1 \leq c_1$: link 1
 $x_1 + x_2 \leq c_2$: link 2
 $x_2 + x_3 \leq c_3$: link 3

Utility Maximization in Networks

Utility $\max_{x_r} \sum_{r \in S} U_r(x_r)$
 Constraints $\sum_{r: l \in r} x_r \leq c_l \quad \forall l \in L$
 $x_r \geq 0 \quad \forall r \in S$



Background - Lagrangian

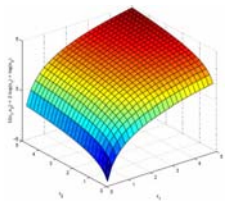
Concave function \leftrightarrow Convex function

$$f(tx + (1-t)y) \geq tf(x) + (1-t)f(y) \quad \alpha \in [0, 1]$$

Strictly concave function

$$f(tx + (1-t)y) > tf(x) + (1-t)f(y) \quad \alpha \in (0, 1)$$

a strictly concave function has a unique maximum



Lagrangian

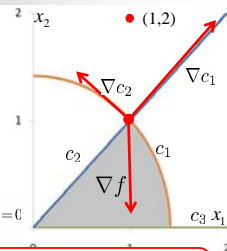
$$L(x, \lambda) = \underbrace{\sum_{r \in S} U_r(x_r)}_{\text{strictly concave}} - \underbrace{\sum_{r: l \in r} \lambda_r (x_r - c_r)}_{\text{convex}} \quad \lambda_r \geq 0$$



Background - Karush-Kuhn-Tucker theorem

example

min $f(x) = (x_1 - 1)^2 + (x_2 - 2)^2$ **convex**
 constraints $c_1(x) = x_1^2 + x_2^2 - 2 \leq 0$
 $c_2(x) = -x_1 + x_2 \leq 0$
 $c_3(x) = -x_2 \leq 0$



$$\nabla f(x^*) - u_1^* \nabla c_1(x^*) - u_2^* \nabla c_2(x^*) = 0$$

$$\begin{pmatrix} 2(x_1^* - 1) \\ 2(x_2^* - 2) \end{pmatrix} + u_1^* \begin{pmatrix} 2x_1^* \\ 2x_2^* \end{pmatrix} + u_2^* \begin{pmatrix} -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 2 \\ 2 \end{pmatrix} + \begin{pmatrix} -1 \\ 1 \end{pmatrix} = 0$$

Karush-Kuhn-Tucker theorem

$$L(x, \lambda) = \sum_{r \in S} U_r(x_r) - \sum_{r: l \in r} \lambda_r (x_r - c_r) \quad \lambda_r \geq 0$$

the optimal value x^* and constraint's grad is Linear independence, then there exists constants λ_r such that

$$\partial L(x^*) / \partial x = 0 \quad \lambda_r (x_r - c_r) = 0$$



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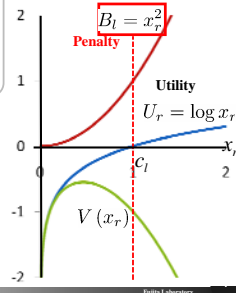
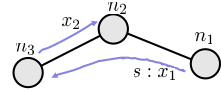
Primal Algorithm - example

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Primal Algorithm - rate-update functions at source side

example

Utility $U_r(x_r) = \log x_r$
 link Penalty $B_1(x_1) = x_1^2$: link 1
 $B_2(x_1 + x_2) = (x_1 + x_2)^2$: link 2
 not to exceed link capacity c_l



$$V(x_r) = \log x_1 + \log x_2 - \{x_1^2 + (x_1 + x_2)^2\}$$

:Utility
:Penalty

We want to maximize $V(x_r)$

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Primal Algorithm - example

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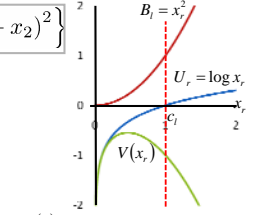
$$V(x_r) = \log x_1 + \log x_2 - \{x_1^2 + (x_1 + x_2)^2\}$$

strictly concave strictly concave convex

when $V(x_r)$ is maximum at point x_1^* and x_2^* ,

$$V'_1(x_1^*) = 1/x_1^* - (4x_1^* + 2x_2^*) = 0$$

$$V'_2(x_2^*) = 1/x_2^* - 2(x_1^* + x_2^*) = 0$$

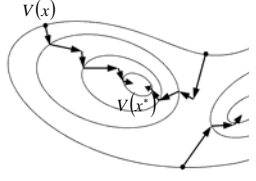


Primal algorithm

$$\dot{x}_1 = k_1(x_1) \{1/x_1 - (4x_1 + 2x_2)\}$$

$$\dot{x}_2 = k_2(x_2) \{1/x_2 - 2(x_1 + x_2)\}$$

$k_r(x_r)$: non-negative, increasing and continuous



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Primal Algorithm - example

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Primal algorithm

$$\dot{x}_1 = k_1(x_1) \{1/x_1 - (4x_1 + 2x_2)\}$$

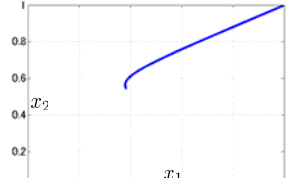
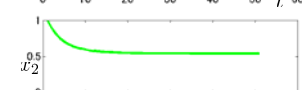
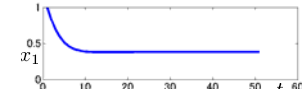
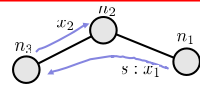
$$\dot{x}_2 = k_2(x_2) \{1/x_2 - 2(x_1 + x_2)\}$$

$$k_1(x_1) = 0.01$$

$$k_2(x_2) = 0.01$$

$$x_1 = 0.3827$$

$$x_2 = 0.5412$$



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Primal Algorithm - Penalty function

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Network utility maximization problem

$$V(x) = \sum_{r \in S} U_r(x_r) - \sum_{l \in L} B_l(y) \quad U_r(x_r) : \text{utility (strictly concave)}$$

$$y = \sum_{s:l \in s} x_s : \text{the arrival rate on a link } l$$

Penalty function

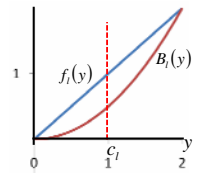
$B_l(\cdot)$ increases when the arrival rate on a link l approaches the link capacity c_l

$$B_l(y) = \int_0^y f_l(y) dy$$

congestion price function

$$f_l(y) = f_l\left(\sum_{s:l \in s} x_s\right) : \text{increasing, continuous function}$$

$$B_l : \text{convex function}$$



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Primal Algorithm

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$$\sum_{r \in S} U_r(x_r) - \sum_{l \in L} B_l(y) = V(x)$$

strictly concave convex strictly concave

$$y = \sum_{s:l \in s} x_s$$

the condition of maximization $V(x)$

$$V'(x_r) = U'_r(x_r) - \sum_{l:l \in r} f_l\left(\sum_{s:l \in s} x_s\right) = 0, \quad r \in S$$

drive x towards the solution of $V(x)$

Primal algorithm

$$\dot{x}_r = k_r(x_r) \left\{ U'_r(x_r) - \sum_{l:l \in r} f_l\left(\sum_{s:l \in s} x_s\right) \right\}$$

$k_r(x_r)$: non-negative, increasing and continuous

drive x_r towards the direction of ascent

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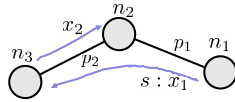
Dual Algorithm - example

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Dual Algorithm - price-update functions on each of links

example

Utility	$U_r(x_r) = \omega_r \log x_r$
Link capacity	$x_1 \leq c_1$: link 1
	$x_1 + x_2 \leq c_2$: link 2



Lagrange dual

$$D(p) = \max_{\{x_r > 0\}} (\omega_1 \log x_1 + \omega_2 \log x_2) - p_1(x_1 - c_1) - p_2(x_1 + x_2 - c_2)$$

constraints

p_l : Lagrange multiplier

The Dual problem

$$\min_{p > 0} D(p)$$

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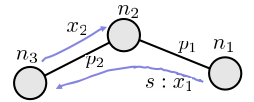


Dual Algorithm - example

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Lagrange dual

$$D(p) = \max_{\{x_r > 0\}} (\omega_1 \log x_1 + \omega_2 \log x_2) - p_1(x_1 - c_1) - p_2(x_1 + x_2 - c_2)$$



The Dual problem

$$\min_{p \geq 0} D(p)$$

$$\text{calculate } \frac{\partial D}{\partial p_l} \Rightarrow \begin{cases} \frac{\partial D}{\partial p_1} = -(x_1 - c_1) > 0 \\ \frac{\partial D}{\partial p_2} = -(x_1 + x_2 - c_2) \geq 0 \end{cases}$$

We need to **descend down** to gradient $D(p)$!

Dual algorithm

$$\begin{aligned} \dot{p}_1 &= (x_1 - c_1)_{p_1}^+ \\ \dot{p}_2 &= (x_1 + x_2 - c_2)_{p_2}^+ \end{aligned} \Rightarrow x_r = \frac{\omega_r}{\sum_l p_l}$$

$$(y_l - c_l)_{p_l}^+ = \begin{cases} y_l - c_l & p_l > 0 \\ \max(y_l - c_l, 0) & p_l = 0 \end{cases}$$

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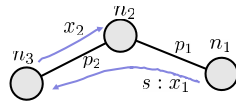


Dual Algorithm - example

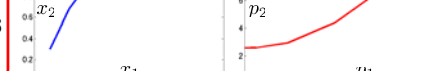
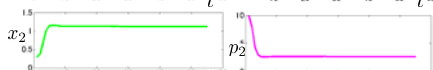
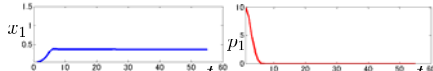
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Dual algorithm

$$\begin{aligned} \dot{p}_1 &= (x_1 - c_1)_{p_1}^+ \\ \dot{p}_2 &= (x_1 + x_2 - c_2)_{p_2}^+ \end{aligned} \Rightarrow x_r = \frac{\omega_r}{\sum_l p_l}$$



$$\begin{aligned} c_1 &= 1.0 \\ c_2 &= 1.5 \\ \omega_1 &= 1.0 \\ \omega_2 &= 3.0 \end{aligned}$$



$$\begin{aligned} x_1 &= 0.3750 \\ x_2 &= 1.1250 \\ p_1 &= -1.2723e-013 \\ p_2 &= 2.6667 \end{aligned}$$

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Dual Algorithm

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resource allocation problem

$$\text{utility } \max_{x_r} \sum_{r \in S} U_r(x_r) \quad \text{constraints } \begin{cases} \sum_{s: l \in s} x_s \leq c_l & \forall l \in L \\ x_r \geq 0 & \forall r \in S \end{cases}$$

Each link has a capacity

The Lagrange dual

$$D(p) = \max_{\{x_r > 0\}} \sum_r U_r(x_r) - \sum_l p_l \left(\sum_{s: l \in s} x_s - c_l \right)$$

constraints

The Dual problem

$$\min_{p > 0} D(p)$$

p_l : Lagrange multiplier
price

To find the direction of a gradient descent, we need to know $\frac{\partial D}{\partial p_l}$

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Dual Algorithm

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Before derive $\frac{\partial D}{\partial p_l}$, we calculate $\frac{\partial D}{\partial x_r}$ and $\frac{\partial U^*}{\partial p_l}$

$$D(p) = \max_{\{x_r > 0\}} \sum_r U_r(x_r) - \sum_l p_l \left(\sum_{s: l \in s} x_s - c_l \right) \quad \because q_r = \sum_{l: l \in r} p_l$$

$$\frac{\partial D}{\partial x_r} = U'(x_r) - q_r = 0 \Rightarrow U''(x_r) \frac{\partial x_r}{\partial p_l} = 1 \quad \text{The price of route } r$$

$$\frac{\partial D}{\partial p_l} = \sum_{r: l \in r} \frac{U'(x_r)}{U''(x_r)} - (y_l - c_l) - \sum_{r: l \in r} p_l \sum_{r: l \in r} \frac{1}{U''(x_r)} \quad \because y_l = \sum_{s: l \in s} x_s$$

The load on link l

$$= c_l - y_l > 0$$

We need to **descend down** to gradient $D(p)$!

Dual algorithm

$$\begin{aligned} \dot{p}_l &= h_l (y_l - c_l)_{p_l}^+ \quad h_l > 0 \\ x_r &= U_r'^{-1}(q_r) \quad (y_l - c_l)_{p_l}^+ = \begin{cases} y_l - c_l & p_l > 0 \\ \max(y_l - c_l, 0) & p_l = 0 \end{cases} \end{aligned}$$

p_l increases when the arrival rate is larger than the capacity

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Outline

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- Background
- Primal Algorithm
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- Primal-Dual Algorithm
- Power network

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Primal-Dual Algorithm

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Primal rate-update functions at source side

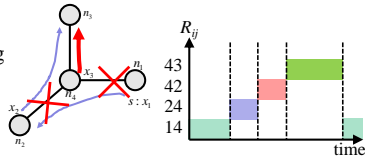
Dual price-update functions on each of links

Exact form of the update were different in the two cases!

in wireless network, interference among various links necessitates scheduling of links

scheduling

R_{ij} : time of rate



Primal-Dual Algorithm

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Primal-Dual Algorithm

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Primal-Dual Algorithm - flow base functions

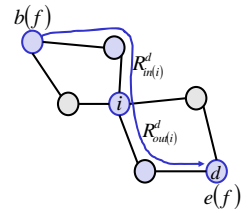
each flow has $\begin{cases} \text{a beginning node } b(f) \\ \text{an ending node } e(f) \end{cases}$

$R_{in(i)}^d$: inflow rate (destination d at node i)

$$\sum_d R_{in(i)}^d = \sum_j R_{ji}$$

$R_{out(i)}^d$: outflow rate (destination d at node i)

$$\sum_d R_{out(i)}^d = \sum_k R_{ik}$$



the arrival rate is less than the departure rate

$$R_{in(i)}^d \leq R_{out(i)}^d$$

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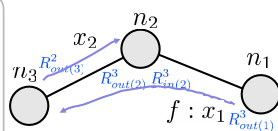
Primal-Dual Algorithm example

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Utility $U_r(x_r) = \omega_r \log x_r$

Constraints

1→3	$x_1 \leq R_{out(1)}^3$
3→2	$x_2 \leq R_{out(3)}^2$
2→3	$R_{in(2)}^3 \leq R_{out(2)}^3$



Lagrange function

$$\max_{x, R > 0} \left\{ \omega_1 \log x_1 + \omega_2 \log x_2 - p_{13} (x_1 - R_{out(1)}^3) - p_{32} (x_2 - R_{out(3)}^2) - p_{23} (R_{in(2)}^3 - R_{out(2)}^3) \right\}$$

Utility constraints

Decoupled

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Primal-Dual Algorithm example

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$$\begin{aligned} & \max_{x \geq 0} \{ \omega_1 \log x_1 + \omega_2 \log x_2 - p_{13} x_1 - p_{32} x_2 \} \\ & \text{the congestion control problem} \\ & + \max_{R \geq 0} \{ p_{13} R_{out(1)}^3 + p_{32} R_{out(3)}^2 + p_{23} (R_{out(2)}^3 - R_{in(2)}^3) \} \\ & \text{the scheduling problem} \end{aligned}$$

Primal-Dual Algorithm

the primal algorithm at each source f

$$\begin{cases} \dot{x}_1(t) = \omega_1/x_1 - p_{13} \\ \dot{x}_2(t) = \omega_2/x_2 - p_{32} \end{cases}$$

the dual algorithm at each $\begin{cases} \text{node } i \\ \text{destination } d \end{cases}$

$$\begin{cases} \dot{p}_{13} = (x_1 - R_{out(1)}^3)_{p_{13}}^+ \\ \dot{p}_{32} = (x_2 - R_{out(3)}^2)_{p_{32}}^+ \\ \dot{p}_{23} = (R_{in(2)}^3 - R_{out(2)}^3)_{p_{23}}^+ \end{cases}$$

calculated at each time instant by solving the scheduling problem

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Primal-Dual Algorithm

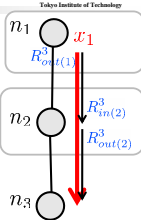
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the optimization problem

$$\max_{x_f, R \geq 0} \sum_f U_f(x_f)$$

each flow constraints

$$i \rightarrow d \quad R_{in(i)}^d + \sum_{f: b(f)=i, e(f)=d} x_f \leq R_{out(i)}^d \quad \forall \text{ nodes } i, d \neq i$$



Lagrange function

$$\max_{x_f, R \geq 0} \sum_f U_f(x_f) - \sum_i \sum_{d \neq i} p_{id} \left(R_{in(i)}^d + \sum_{f: b(f)=i, e(f)=d} x_f - R_{out(i)}^d \right)$$

p_{id} : Lagrange multiplier

Decoupled

$$\max_{x_f \geq 0} \left\{ \sum_f U_f(x_f) - \sum_f p_{b(f)e(f)} x_f \right\} + \max_{R \geq 0} \left\{ \sum_i \sum_{d \neq i} p_{id} (R_{in(i)}^d - R_{out(i)}^d) \right\}$$

x_f 's terms R 's terms

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Primal-Dual Algorithm

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Lagrange function

$$\max_{x_f \geq 0} \left\{ \sum_f U_f(x_f) - \sum_f p_{b(f)e(f)} x_f \right\} + \max_{R \geq 0} \left\{ \sum_i \sum_{d \neq i} p_{id} (R_{in(i)}^d - R_{out(i)}^d) \right\}$$

the congestion control problem the scheduling problem

Primal-Dual Algorithm to solve the congestion control problem

the primal algorithm at each source f

$$\dot{x}_f(t) = U_f'(x_f) - p_{b(f)e(f)}$$

the dual algorithm at each $\begin{cases} \text{node } i \\ \text{destination } d \end{cases}$

$$\dot{p}_{id} = \left\{ \sum_{f: b(f)=i, e(f)=d} x_f(t) + R_{in(i)}^d - R_{out(i)}^d \right\}_{p_{id}}^+$$

calculated at each time instant by solving the scheduling problem

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- **Power network**

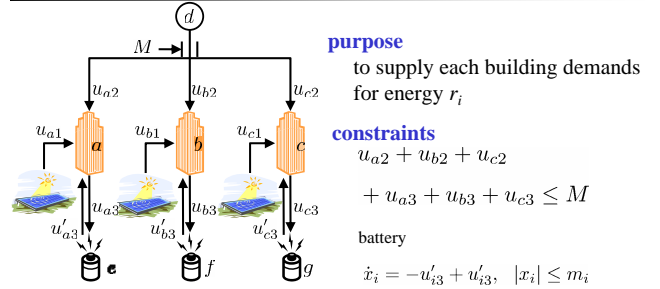
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Power network

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purpose
to supply each building demands for energy r_i

constraints

$$u_{a2} + u_{b2} + u_{c2} + u_{a3} + u_{b3} + u_{c3} \leq M$$

battery

$$\dot{x}_i = -u'_{i3} + u'_{i3}, \quad |x_i| \leq m_i$$

Utility function

purpose

battery

$$\min_{u_{i2} \geq 0, u_{i3}} \sum_{i=a}^c \left\{ q_{1i} \exp(u_{i1} + u_{i2} + u_{i3} - u'_{i3} - r_i) + q_{2i} \exp\left(m_i - \int_{t_0}^T u_{i3} dt + \int_{t_0}^T u'_{i3} dt\right) \right\}$$

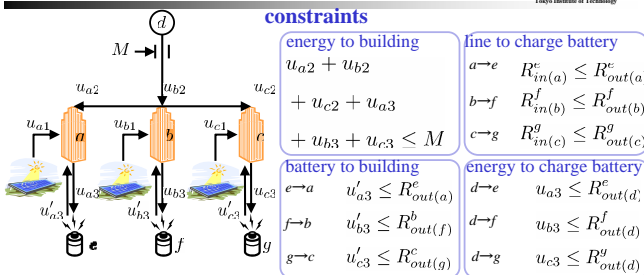
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Power network

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constraints

energy to building

$$u_{a2} + u_{b2} + u_{c2} + u_{a3} + u_{b3} + u_{c3} \leq M$$

line to charge battery

$$\begin{aligned} a \rightarrow e & R_{in}^e(a) \leq R_{out}^e(a) \\ b \rightarrow f & R_{in}^f(b) \leq R_{out}^f(b) \\ c \rightarrow g & R_{in}^g(c) \leq R_{out}^g(c) \end{aligned}$$

battery to building

$$\begin{aligned} e \rightarrow a & u'_{a3} \leq R_{out}^e(a) \\ f \rightarrow b & u'_{b3} \leq R_{out}^f(b) \\ g \rightarrow c & u'_{c3} \leq R_{out}^g(c) \end{aligned}$$

energy to charge battery

$$\begin{aligned} d \rightarrow e & u_{a3} \leq R_{out}^d(e) \\ d \rightarrow f & u_{b3} \leq R_{out}^d(f) \\ d \rightarrow g & u_{c3} \leq R_{out}^d(g) \end{aligned}$$

Lagrange function

$$\begin{aligned} \min_{u_{i2} \geq 0, u_{i3}} \sum_{i=a}^c \left\{ q_{1i} \exp(u_{i1} + u_{i2} + u_{i3} - u'_{i3} - r_i) + q_{2i} \exp\left(m_i - \int_{t_0}^T u_{i3} dt + \int_{t_0}^T u'_{i3} dt\right) \right\} \\ - p_1 \left(\sum_{i=a}^c u_{i2} + \sum_{i=a}^c u_{i3} - M \right) - \sum_{i=a, j=e}^{c, g} \left\{ p_{2i} (R_{in}^j(i) - R_{out}^j(i)) + p_{3i} (u_{i3} - R_{out}^j(i)) \right\} - \sum_{i=a, j=e}^{c, g} p_{4i} (u_{i3} - R_{out}^j(i)) \end{aligned}$$

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Power network

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$$\begin{aligned} \min_{u_{i2} \geq 0, u_{i3}} \sum_{i=a}^c \left\{ q_{1i} \exp(u_{i1} + u_{i2} + u_{i3} - u'_{i3} - r_i) \right. \\ \left. + q_{2i} \exp\left(m_i - \int_{t_0}^T u_{i3} dt + \int_{t_0}^T u'_{i3} dt\right) - \left\{ p_1(u_{i2} + u_{i3}) + p_{3i}u'_{i3} + p_{4i}u_{i3} \right\} \right\} \\ \min_R \sum_{i=a, j=e}^{c, g} \left\{ p_{2i} (R_{in}^j(i) - R_{out}^j(i)) + p_{3i}R_{out}^j(j) + p_{4i}R_{out}^j(d) \right\} \end{aligned}$$

the congestion control problem
the scheduling problem

Primal-Dual Algorithm

the primal algorithm

$$\begin{aligned} \dot{u}_{i2} &= q_{1i} \exp(u_{i1} + u_{i2} + u_{i3} - u'_{i3} - r_i) - p_1 \\ \dot{u}_{i3} &= q_{1i} \exp(u_{i1} + u_{i2} + u_{i3} - u'_{i3} - r_i) - p_1 - p_{4i} \\ &\quad + q_{2i} (u_{i3}|_{t_0} - u_{i3}|_T) \exp\left(m_i - \int_{t_0}^T u_{i3} dt + \int_{t_0}^T u'_{i3} dt\right) \\ \dot{u}'_{i3} &= q_{1i} \exp(u_{i1} + u_{i2} + u_{i3} - u'_{i3} - r_i) - p_{3i} \\ &\quad + q_{2i} (u'_{i3}|_{t_0} - u'_{i3}|_T) \exp\left(m_i - \int_{t_0}^T u_{i3} dt + \int_{t_0}^T u'_{i3} dt\right) \end{aligned}$$

the dual algorithm

$$\begin{aligned} \dot{p}_1 &= \left(\sum_{i=a}^c u_{i2} + \sum_{i=a}^c u_{i3} - M \right)_{p_1}^+ \\ \dot{p}_{2i} &= \left(R_{in}^j(i) - R_{out}^j(i) \right)_{p_{2i}}^+ \\ \dot{p}_{3i} &= \left(u_{i3} - R_{out}^j(j) \right)_{p_{3i}}^+ \\ \dot{p}_{4i} &= \left(u_{i3} - R_{out}^j(j) \right)_{p_{4i}}^+ \end{aligned}$$

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